Forklift Control Valves

Forklift Control Valve - The earliest mechanized control systems were being used over two thousand years ago. In Alexandria Egypt, the ancient Ktesibios water clock built in the 3rd century is considered to be the first feedback control equipment on record. This particular clock kept time by regulating the water level in a vessel and the water flow from the vessel. A common design, this successful equipment was being made in a similar manner in Baghdad when the Mongols captured the city in 1258 A.D.

A variety of automatic devices through history, have been used so as to complete particular tasks. A popular desing used during the seventeenth and eighteenth centuries in Europe, was the automata. This particular piece of equipment was an example of "openloop" control, comprising dancing figures that would repeat the same task repeatedly.

Closed loop or feedback controlled tools comprise the temperature regulator common on furnaces. This was actually developed during 1620 and accredited to Drebbel. One more example is the centrifugal fly ball governor developed during 1788 by James Watt and used for regulating steam engine speed.

The Maxwell electromagnetic field equations, discovered by J.C. Maxwell wrote a paper in 1868 "On Governors," which was able to describing the exhibited by the fly ball governor. To explain the control system, he made use of differential equations. This paper demonstrated the importance and helpfulness of mathematical models and methods in relation to understanding complicated phenomena. It likewise signaled the start of mathematical control and systems theory. Previous elements of control theory had appeared earlier by not as convincingly and as dramatically as in Maxwell's analysis.

New developments in mathematical techniques and new control theories made it possible to more precisely control more dynamic systems as opposed to the original model fly ball governor. These updated methods comprise different developments in optimal control during the 1950s and 1960s, followed by development in robust, stochastic, adaptive and optimal control methods during the 1970s and the 1980s.

New applications and technology of control methodology has helped make cleaner engines, with more efficient and cleaner methods helped make communication satellites and even traveling in space possible.

Initially, control engineering was performed as just a part of mechanical engineering. Control theories were originally studied with electrical engineering since electrical circuits can simply be described with control theory methods. Currently, control engineering has emerged as a unique discipline.

The first controls had current outputs represented with a voltage control input. So as to implement electrical control systems, the right technology was unavailable at that moment, the designers were left with less efficient systems and the choice of slow responding mechanical systems. The governor is a really effective mechanical controller that is still usually used by various hydro factories. Ultimately, process control systems became offered previous to modern power electronics. These process controls systems were usually utilized in industrial applications and were devised by mechanical engineers using hydraulic and pneumatic control equipments, a lot of which are still being used at present.